# Table of Contents

- Overview .................................................................................................................. 5
- Key Features .................................................................................................................. 5
- Revision History .......................................................................................................... 5
- Release Notes and Know Issues .................................................................................. 5
- Requirements ............................................................................................................... 5
  - Software .................................................................................................................. 5
  - Hardware .................................................................................................................. 6
- Content .......................................................................................................................... 7
  - Design Sources .......................................................................................................... 7
  - Additional Sources ..................................................................................................... 7
  - Prebuilt ...................................................................................................................... 7
  - Download .................................................................................................................. 7
- Design Flow .................................................................................................................... 9
- Launch ............................................................................................................................. 11
  - Programming ............................................................................................................. 11
    - QSPI ....................................................................................................................... 11
    - SD .......................................................................................................................... 11
    - JTAG ....................................................................................................................... 11
  - Usage ............................................................................................................................ 11
    - Linux ....................................................................................................................... 12
    - Vivado HW Manager ............................................................................................... 12
- System Design - Vivado ............................................................................................... 13
  - Block Design ............................................................................................................. 13
  - PS Interfaces .............................................................................................................. 13
  - Constrains ................................................................................................................ 14
    - Basic module constrains ......................................................................................... 14
    - Design specific constrain ....................................................................................... 14
- Software Design - SDK/HSI ......................................................................................... 15
  - Application ................................................................................................................. 15
    - FSBL ....................................................................................................................... 15
    - U-Boot .................................................................................................................... 15
- Software Design - PetaLinux ....................................................................................... 16
  - Config ......................................................................................................................... 16
  - U-Boot ......................................................................................................................... 16
  - Device Tree ............................................................................................................... 17
  - Kernel ......................................................................................................................... 18
  - Rootfs ......................................................................................................................... 18
  - Applications .............................................................................................................. 18
    - startup .................................................................................................................... 18
- Additional Software ...................................................................................................... 19
- Appx. A: Change History and Legal Notices ............................................................... 20
  - Document Change History ....................................................................................... 20
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Legal Notices</td>
<td>20</td>
</tr>
<tr>
<td>Data privacy</td>
<td>20</td>
</tr>
<tr>
<td>Document Warranty</td>
<td>20</td>
</tr>
<tr>
<td>Limitation of Liability</td>
<td>21</td>
</tr>
<tr>
<td>Copyright Notice</td>
<td>21</td>
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<tr>
<td>Technology Licenses</td>
<td>21</td>
</tr>
<tr>
<td>Environmental Protection</td>
<td>21</td>
</tr>
<tr>
<td>REACH, RoHS and WEEE</td>
<td>22</td>
</tr>
</tbody>
</table>
Online version of this manual and other related documents can be found at https://wiki.trenz-electronic.de/display/PD/Trenz+Electronic+Documentation
Overview

Zynq Design PS with Linux and simple frequency counter to measure MGT Reference CLK with Vivado HW-Manager.

Key Features

- PetaLinux
- SD
- ETH
- USB
- I2C
- RTC
- FMeter

Revision History

<table>
<thead>
<tr>
<th>Date</th>
<th>Vivado</th>
<th>Project Built</th>
<th>Authors</th>
<th>Description</th>
</tr>
</thead>
</table>
| 2017-10-19 | 2017.2 | te0715-test_board-vivado_2017.2-build_04_20171019141808.zip  | John Hartfiel | ● changed Flash typ on TE0715_board_files.csv  
(older one is not supported on Vivado 2017.2) |
|          |        | te0715-test_board_noprebuilt-vivado_2017.2-build_04_20171019141825.zip |            |                                                                            |
| 2017-09-22 | 2017.2 | te0715-test_board-vivado_2017.2-build_02_20170927143412.zip | John Hartfiel | initial release                                                             |
|          |        | te0715-test_board_noprebuilt-vivado_2017.2-build_02_20170927143427.zip |            |                                                                            |

Release Notes and Known Issues

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<th>Issues</th>
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<th>Workaround</th>
<th>To be fixed version</th>
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<tr>
<td>No known issues</td>
<td>---</td>
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Requirements

Software

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<th>Version</th>
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<td>Vivado</td>
<td>2017.2</td>
<td>needed</td>
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<tr>
<td>SDK</td>
<td>2017.2</td>
<td>needed</td>
</tr>
<tr>
<td>PetaLinux</td>
<td>2017.2</td>
<td>needed</td>
</tr>
</tbody>
</table>
Hardware

Basic description of TE Board Part Files is available on TE Board Part Files.

Complete List is available on <design name>/board_files/*_board_files.csv

Design supports following modules:

<table>
<thead>
<tr>
<th>Module Model</th>
<th>Board Short Name</th>
<th>PCB Revision Support</th>
<th>Notes</th>
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<tbody>
<tr>
<td>te0715-03-15-1c</td>
<td>03_15_1c</td>
<td>REV01,02,03</td>
<td></td>
</tr>
<tr>
<td>te0715-03-15-1i</td>
<td>03_15_1i</td>
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<tr>
<td>te0715-03-15-2i</td>
<td>03_15_2i</td>
<td>REV01,02,03</td>
<td></td>
</tr>
<tr>
<td>te0715-03-30-1c</td>
<td>03_30_1c</td>
<td>REV01,02,03</td>
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</tr>
<tr>
<td>te0715-03-30-1i</td>
<td>03_30_1i</td>
<td>REV01,02,03</td>
<td></td>
</tr>
<tr>
<td>te0715-03-30-3e</td>
<td>03_30_3e</td>
<td>REV01,02,03</td>
<td></td>
</tr>
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</tr>
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<td>REV04</td>
<td></td>
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<tr>
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<td>04_30_1i</td>
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<td>04_30_3e</td>
<td>REV04</td>
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<td>12s</td>
<td>REV04</td>
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Design supports following carriers:

<table>
<thead>
<tr>
<th>Carrier Model</th>
<th>Notes</th>
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<tbody>
<tr>
<td>TE0701</td>
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<tr>
<td>TE0703</td>
<td></td>
</tr>
<tr>
<td>TE0705</td>
<td></td>
</tr>
<tr>
<td>TE0706</td>
<td>used as reference carrier</td>
</tr>
<tr>
<td>TEBA0841</td>
<td></td>
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Additional HW Requirements:

<table>
<thead>
<tr>
<th>Additional Hardware</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>USB Cable for JTAG/UART</td>
<td>Check Carrier Board and Programmer for correct typ</td>
</tr>
<tr>
<td>XMOD Programmer</td>
<td>Carrier Board dependent, only if carrier has no own FTDI</td>
</tr>
</tbody>
</table>
Content

For general structure and of the reference design, see Project Delivery

Design Sources

<table>
<thead>
<tr>
<th>Type</th>
<th>Location</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vivado</td>
<td>&lt;design name&gt;/block_design</td>
<td>Vivado Project will be generated by TE Scripts</td>
</tr>
<tr>
<td></td>
<td>&lt;design name&gt;/constraints</td>
<td></td>
</tr>
<tr>
<td></td>
<td>&lt;design name&gt;/ip_lib</td>
<td></td>
</tr>
<tr>
<td>SDK/HSI</td>
<td>&lt;design name&gt;/sw_lib</td>
<td>Additional Software Template for SDK/HSI and apps_list.csv with settings for HSI</td>
</tr>
<tr>
<td>PetaLinux</td>
<td>&lt;design name&gt;/os/petalinux</td>
<td>PetaLinux template with current configuration</td>
</tr>
</tbody>
</table>

Additional Sources

<table>
<thead>
<tr>
<th>Type</th>
<th>Location</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Prebuilt

Only on ZIP file with Prebuilt content.

<table>
<thead>
<tr>
<th>File</th>
<th>File-Extension</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BIF-File</td>
<td>*.bif</td>
<td>File with description to generate Bin-File</td>
</tr>
<tr>
<td>BIN-File</td>
<td>*.bin</td>
<td>Flash Configuration File with Boot-Image (Zynq-FPGAs)</td>
</tr>
<tr>
<td>BIT-File</td>
<td>*.bit</td>
<td>FPGA (PL Part) Configuration File</td>
</tr>
<tr>
<td>DebugProbes-File</td>
<td>*.ltx</td>
<td>Definition File for Vivado/Vivado Labtools Debugging Interface</td>
</tr>
<tr>
<td>Diverse Reports</td>
<td>...</td>
<td>Report files in different formats</td>
</tr>
<tr>
<td>Hardware-Platform-Specification-Files</td>
<td>*.hdf</td>
<td>Exported Vivado Hardware Specification for SDK/HSI and PetaLinux</td>
</tr>
<tr>
<td>LabTools Project-File</td>
<td>*.lpr</td>
<td>Vivado Labtools Project File</td>
</tr>
<tr>
<td>OS-Image</td>
<td>*.ub</td>
<td>Image with Linux Kernel (On Petalinux optional with Devicetree and RAM-Disk)</td>
</tr>
<tr>
<td>Software-Application-File</td>
<td>*.elf</td>
<td>Software Application for Zynq or MicroBlaze Processor Systems</td>
</tr>
</tbody>
</table>

Download

Reference Design is only usable with the specified Vivado/SDK/PetaLinux/SDx version. Do never use different Versions of Xilinx Software for the same Project.

Reference Design is available on:
• TE0715 "Test Board" Reference Design Download Area
Design Flow

Reference Design is available with and without prebuilt files. It’s recommended to use TE prebuilt files for first lunch.

Trenz Electronic provides a tcl based built environment based on Xilinx Design Flow.

See also:

- Vivado/SDK/SDSoC#XilinxSoftware-BasicUserGuides
- Vivado Projects
- Project Delivery.

The Trenz Electronic FPGA Reference Designs are TCL-script based project. Command files for execution will be generated with ".create_win_setup.cmd” on Windows OS and ".create_linux_setup.sh” on Linux OS.

TE Scripts are only needed to generate the vivado project, all other additional steps are optional and can also executed by Xilinx Vivado/SDK GUI. For currently Scripts limitations on Win and Linux OS see: Project Delivery Currently limitations of functionality

1. Run _create_win_setup.cmd/_create_linux_setup.sh and follow instructions on shell:

   ![Command prompt](image)

   - Run Design with: create_win_setup
   - Use Design Path: Bi:Design\cores\2017.1\design\TE0715\test_board\setLocal
   - _TE Reference Design_

   - (c) Go to CMD-File Generation (Manual setup)
   - (d) Go to Documentation (Web Documentation)
   - (e) Exit Batch (nothing is done)
   - (f) Create minimum setup of CMD-Files and exit Batch
   - (g) Create maximum setup of CMD-Files and exit Batch

   Select (ex.'0' for min setup):

2. Press 0 and enter for minimum setup
3. (optional Win OS) Generate Virtual Drive or use short directory for the reference design (for example x:\<design name>)
4. Create Project
   a. Select correct device and Xilinx install path on "design_basic_settings.cmd” and create Vivado project with "vivado_create_project_guiMode.cmd”

   Note: Select correct one, see TE Board Part Files
5. Create HDF and export to prebuilt folder
   a. Run on Vivado TCL: TE::hw_build_design -export_prebuilt
      Note: Script generate design and export files into \prebuilt\hardware\<short dir>. Use GUI is
      the same, except file export to prebuilt folder
6. Create Linux (uboot.elf and image.ub) with exported HDF
   a. HDF is exported to "prebuilt\hardware\<short name>"
      Note: HW Export from Vivado GUI create another path as default workspace.
   b. Create Linux images on VM, see PetaLinux KICKstart
      i. Use TE Template from /os/petalinux
         Note: run init_config.sh before you start petalinux config. This will set correct temporary
         path variable.
7. Add Linux files (uboot.elf and image.ub) to prebuilt folder
   a. "prebuilt\os\petalinux\default" or "prebuilt\os\petalinux\<short name>"
      Notes: Scripts select "prebuilt\os\petalinux\<short name>", if exist, otherwise
      "prebuilt\os\petalinux\default"
8. Generate Programming Files with HSI/SDK
   a. Run on Vivado TCL: TE::sw_run_hsi
      Note: Scripts generate applications and bootable files, which are defined in "sw_lib\apps_list.
      csv"
   b. (alternative) Start SDK with Vivado GUI or start with TE Scripts on Vivado TCL: TE::
      sw_run_sdk
      Note: See SDK Projects
Launch

⚠️ Check Module and Carrier TRMs for proper HW configuration before you try any design.

Reference Design is also available with prebuilt files. It's recommended to use TE prebuilt files for first lunch.

TE0715-0x-30-xx only: HP IO Banks max power supply voltage is 1.8V.

Programming

Xilinx documentation for programming and debugging: Vivado/SDK/SDSoC-Xilinx Software Programming and Debugging

QSPI

Not used on this Example.

SD

1. Copy image.ub and Boot.bin on SD-Card.
   - For correct prebuilt file location, see <design_name>/prebuilt/readme_file_location.txt
2. Set Boot Mode to SD-Boot.
   - Depends on Carrier, see carrier TRM.
3. Insert SD-Card in SD-Slot.

JTAG

Not used on this Example.

Usage

1. Prepare HW like described on section Programming
2. Connect UART USB (most cases same as JTAG)
3. Select SD Card as Boot Mode
   - Note: See TRM of the Carrier, which is used.
4. Power On PCB
   - Note: 1. Zynq Boot ROM loads FSBL from SD into OCM, 2. FSBL loads U-boot from SD into DDR, 3. U-boot load Linux from SD into DDR
Linux

1. Open Serial Console (e.g. putty)
   a. Speed: 115200
   b. COM Port: Win OS, see device manager, Linux OS see dmesg |grep tty (UART is *USB1)

2. Linux Console:
   Note: Wait until Linux boot finished For Linux Login use:
   a. User Name: root
   b. Password: root

3. You can use Linux shell now.
   a. i2C 1 Bus type: i2cdetect -y -r 1
   b. RTC check: dmesg | grep rtc
   c. ETH0 works with udhcpc

Vivado HW Manager

MGT Reference CLK Counter:

1. Open Vivado HW-Manager and add VIO signal to dashboard (*.ltx located on prebuilt folder).
   a. Set radix from VIO signals to unsigned integer.
      Note: Frequency Counter is inaccurate and displayed unit is Hz

MGT CLK is configured to 125MHz by default, FCLK is not configured by default.
**System Design - Vivado**

**Block Design**

---

**PS Interfaces**

Activated interfaces:

<table>
<thead>
<tr>
<th>Type</th>
<th>Note</th>
</tr>
</thead>
<tbody>
<tr>
<td>DDR</td>
<td>---</td>
</tr>
<tr>
<td>QSPI</td>
<td>MIO</td>
</tr>
<tr>
<td>I2C0</td>
<td>EMIO-NC</td>
</tr>
<tr>
<td>I2C1</td>
<td>MIO</td>
</tr>
<tr>
<td>UART0</td>
<td>MIO</td>
</tr>
<tr>
<td>GPIO</td>
<td>MIO</td>
</tr>
<tr>
<td>SD0</td>
<td>MIO</td>
</tr>
</tbody>
</table>
## Constrains

### Basic module constrains

```xdc
set_property BITSTREAM.GENERAL.COMPRESS TRUE [current_design]
set_property CONFIG_VOLTAGE 3.3 [current_design]
set_property CFGBVS VCCO [current_design]
set_property BITSTREAM.CONFIG.USR_ACCESS TIMESTAMP [current_design]
```

```xdc
set_property BITSTREAM.CONFIG.UNUSEDPIN PULLNONE [current_design]
```

### Design specific constrain

```xdc
set_property PACKAGE_PIN K2 [get_ports {fclk[0]}]
set_property IOSTANDARD LVCMOS18 [get_ports {fclk[0]}]
set_property CLOCK_DEDICATED_ROUTE FALSE [get_nets fclk_IBUF[0]]
```
Software Design - SDK/HSI

For SDK project creation, follow instructions from:

- SDK Projects

Application

FSBL

Xilinx default FSBL

U-Boot

U-Boot.elf is generated with PetaLinux. SDK/HSI is used to generate Boot.bin.
Software Design - PetaLinux

For PetaLinux installation and project creation, follow instructions from:

- PetaLinux KICKstart

Config

No changes.

U-Boot

No changes.
Device Tree

```
#include/"system-conf.dtsi"
/

/

/* default */

/* ETH PHY */
&gem0 {

  status = "okay";
  ethernet_phy0: ethernet-phy0 {
    compatible = "marvell,88e1510";
    device_type = "ethernet-phy";
    reg = <0>;
  }
}

/* USB PHY */
&usb Phy0: usb_phy@0 {
  compatible = "ulpi-phy";
  //compatible = "usb-nop-xceiv";
  #phy-cells = <0>;
  reg = <0xe0002000 0x1000>
  view-port = <0x0170>
  drv-vbus;
}

&usb0 {
  dr_mode = "host";
  //dr_mode = "Peripheral";
  usb-phy = &usb_phy0;
}

/* I2C */
// i2c PLL: 0x70, i2c eeprom: 0x50

&i2c1 {
  rtc@6F {
    // Real Time Clock
    compatible = "isl12022";
    reg = <0x6F>;
  }
}
```
Kernel

Activate:

- RTC_DRV_ISL12022

Rootfs

Activate:

- i2c-tools

Applications

startup

Script App to load init.sh from SD Card if available.

See: `os/petlinux/project-spec/meta-user/recipes-apps/startup/files`
Additional Software

No additional software is needed.
Appx. A: Change History and Legal Notices

Document Change History

To get content of older revision got to "Change History" of this page and select older document revision number.

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<tr>
<th>Date</th>
<th>Document Revision</th>
<th>Authors</th>
<th>Description</th>
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<td>2018-10-01</td>
<td>v.31</td>
<td>John Hartfiel</td>
<td>• Download Update</td>
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<td>2017-10-19</td>
<td>v.20</td>
<td>John Hartfiel</td>
<td>• Document style update</td>
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<td>2017-10-06</td>
<td>v.18</td>
<td>John Hartfiel</td>
<td>• Text correction</td>
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<td>• Update Launch section</td>
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<td>• Supported PCBs</td>
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<td>2017-10-02</td>
<td>v.14</td>
<td>John Hartfiel</td>
<td>• Document update on Prebuilt section</td>
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<td>2017-09-28</td>
<td>v.13</td>
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<td>Release 2017.2</td>
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<td>Initial release</td>
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2018-09-18